

Project Stakeholders

- Urban Systems
- DMD & Associates
- BC Ministry of Transportation and Infrastructure
- US Customs & Border Protection (USCBP)
- Cobra Electric

Project Primary Objectives

- Provide priority system for "FAST" commercial vehicles
- Improve efficiency for all vehicles in the staging area

Improve storage capacity in truck staging area





Project Objectives

- Design a control system to provide maximum flexibility
- Provided method for USCBP officials to control & monitoring the system





Project Challenges

- Critical project timeline
- Meet current and future requirements
- Accurately detect vehicles of all sizes
- Driver behavior & enforcement

System Overview



















RUN

Remote Lane Control System for US Customs & Border Protection (USBP)

- Remote Control at US Customs & Border Protection Entry Lanes
- Remote Control at US Customer & Border Protection "FAST"

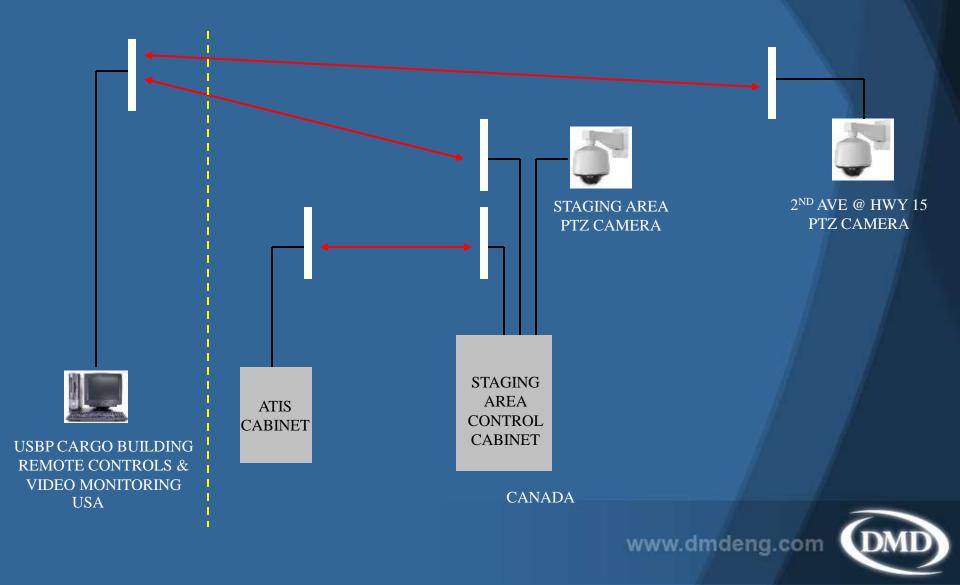
 Lanes
- Future control for other lanes or functions

US Border Entry Lanes		
Lane 1	Lane 1 Closed	Closed Open
Lane 2	Lane 2 Open	Closed Open
Lane 3	Lane 3 Open	Closed Open





Video Communications and ATIS Integration



Video Monitoring System

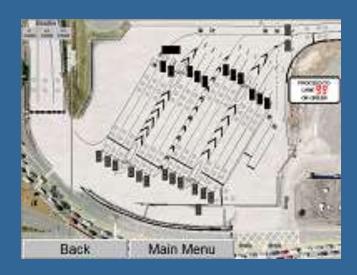
- Pan, Tilt, Zoom (PTZ) VideoMonitoring Cameras System
- Violations monitoring
- Incident Management monitoring





PLC Control Logic

- Dynamic vs. Static
- Comprehensive testing and debugging performed prior to installation





Vehicle Detection System



Video Detection



Microwave Detection



Inductive Loop Detection



Lessons Learned

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- Allow ample time to undertake project
- Enforcement key to changing driver behavior



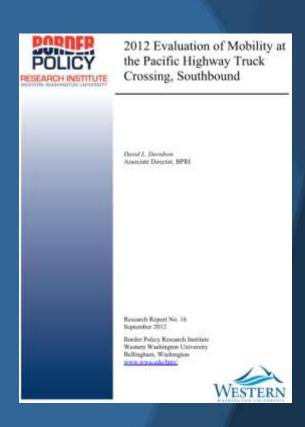






Independent System Evaluation

- Western Washington University –Study (www.wwu.edu/bpri/vehicles)
- Overall reduction in wait times for all commercial trucks
- Further reduction in wait times for new "FAST" lane access











Questions?

